# Improved entropy based test of uniformity using ranked set samples

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#### **Abstract**

Ranked set sampling (RSS) is known to be superior to the traditional simple random sampling (SRS) in the sense that it often leads to more efficient inference procedures. Basic version of RSS has been extensively modified to come up with schemes resulting in more accurate estimators of the population attributes. Multistage ranked set sampling (MSRSS) is such a variation surpassing RSS. Entropy has been instrumental in constructing criteria for fitting of parametric models to the data. The goal of this article is to develop tests of uniformity based on sample entropy under RSS and MSRSS designs. A Monte Carlo simulation study is carried out to compare the power of the proposed tests under several alternative distributions with the ordinary test based on SRS. The results report that the new entropy tests have higher power than the original one for nearly all sample sizes and under alternatives considered.

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#### 1. Introduction

When the sampling units are difficult to measure but are reasonably simple and cheap to order according to the variable of interest, ranked set sampling (RSS) serves as an appealing alternative to the usual simple random sampling (SRS). Examples of this setup can be found in areas such as agriculture, environment and ecology. The RSS design works by ranking randomly drawn sampling units and quantifying a selected subset of them. McIntyre (1952) introduced this sampling technique while studying the yield of pasture in Australia. He suggested that a fairly accurate ordering of a set of adjacent plots by yield can be made using visual perception, although measuring the

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yield of each plot is expensive. As a similar situation, consider the following example mentioned by Gulati (2004). Suppose it is of interest to count the number of specific bacterial cells per unit volume in a cell suspension. A set of test tubes, containing the cell suspension, can be ordered by concentration using an optical device without actual measurement on them.

The RSS method can be elucidated as follows.

- 1. Draw *k* random samples, each of size *k*, from the target population.
- 2. Apply judgement ordering, by any cheap method, on the elements of the *i*th (i = 1, ..., k) sample and identify the *i*th smallest unit.
- 3. Actually measure the *k* identified units in step 2.
- 4. Repeat steps 1-3, h times (cycles), if necessary, to obtain a ranked set sample of size n = hk.

The set of measured observations makes up a ranked set sample of size n denoted by  $\{X_{[i]j}: i=1,\ldots,k; j=1,\ldots,h\}$ , where  $X_{[i]j}$  is the ith judgement order statistic from the jth cycle. To have better understanding of difference between the ranked set sample and simple ranked set sample of the same size, we consider the case of single cycle (h=1) and perfect judgement ranking. In this case, the ranked set sample observations are also the respective order statistics. Let  $X_1,\ldots,X_k$  be a simple random sample of size k from a continuous population with probability density function (PDF) f(x) and cumulative distribution function (CDF) F(x), and let  $X_{[1]},\ldots,X_{[k]}$  denote a ranked set sample of size k obtained as described above.

In the SRS case, the k observations are independent and each of them represents a typical value from the population. Letting  $X_{(1)} \leq \ldots \leq X_{(k)}$  be the order statistics associated with these SRS observations, we note that they are dependent random variables with joint PDF given by

$$g_{SRS}(x_{(1)},...,x_{(k)}) = k! \prod_{i=1}^{k} f(x_{(i)}).$$

In the RSS settings, additional information and structure is provided by through the judgement ranking process. The k measurements  $X_{[1]}, \ldots, X_{[k]}$  are also order statistics but in this case they are independent observations and each of them provides information about a different aspect of the population. The joint PDF for  $X_{[1]}, \ldots, X_{[k]}$  is given by

$$g_{\text{RSS}}(x_{[1]},\ldots,x_{[k]}) = \prod_{i=1}^{k} f_i(x_{[i]}),$$

where  $f_i(.)$  is the PDF for the *i*th order statistic of a simple random sample of size k from the target population. It is this extra structure provided by judgement ranking and

the independence of the resulting order statistics that enables RSS-based procedures to be more efficient than their RSS competitors with the same number of quantified units. A detailed discussion on the theory and applications of RSS can be found in the recent book by Chen et al. (2004).

Consider estimating the population mean under the aforesaid designs. Let  $\bar{X}_{SRS} = \sum_{i=1}^k X_i/k$  and  $\bar{X}_{RSS} = \sum_{i=1}^k X_{[i]}/k$  be the SRS and RSS sample mean, respectively. Hence, we have

$$E(\bar{X}_{RSS}) = \frac{1}{k} \sum_{i=1}^{k} \left\{ \int_{-\infty}^{\infty} kx \binom{k-1}{i-1} [F(x)]^{i-1} [1 - F(x)]^{k-i} f(x) dx \right\}$$

$$= \int_{-\infty}^{\infty} x f(x) \left\{ \sum_{i=1}^{k} \binom{k-1}{i-1} [F(x)]^{i-1} [1 - F(x)]^{k-i} \right\} dx. \tag{1}$$

Since the summation in equation (1) is just the sum over entire sample space of the probabilities for a binomial random variable with parameters k-1 and F(x), it follows that

$$E(\bar{X}_{RSS}) = \int_{-\infty}^{\infty} x f(x) \, dx = \mu.$$

Letting  $\mu_{[i]} = E(X_{[i]})$ , for i = 1, ..., k, we note that

$$\mathrm{E}(X_{[i]} - \mu)^2 = \mathrm{E}(X_{[i]} - \mu_{[i]} + \mu_{[i]} - \mu)^2 = \mathrm{E}(X_{[i]} - \mu_{[i]})^2 + (\mu_{[i]} - \mu)^2,$$

since the cross-product terms are zero. So

$$\operatorname{Var}(\bar{X}_{RSS}) = \frac{1}{k^2} \left\{ \sum_{i=1}^k \operatorname{E}(X_{[i]} - \mu)^2 - \sum_{i=1}^k (\mu_{[i]} - \mu)^2 \right\}.$$
 (2)

Now, proceeding as we did with  $E(\bar{X}_{RSS})$ , we see that

$$\begin{split} \sum_{i=1}^k \mathbf{E}(X_{[i]} - \mu)^2 &= \sum_{i=1}^k \int_{-\infty}^{\infty} k(x - \mu)^2 \binom{k-1}{i-1} [F(x)]^{i-1} [1 - F(x)]^{k-i} f(x) \, dx \\ &= k \int_{-\infty}^{\infty} (x - \mu)^2 f(x) \Big\{ \sum_{i=1}^k \binom{k-1}{i-1} [F(x)]^{i-1} [1 - F(x)]^{k-i} \Big\} \, dx. \end{split}$$

Once again, using the binomial expansion, the interior sum is equal to 1 and we obtain

$$\sum_{i=1}^{k} E(X_{[i]} - \mu)^2 = k \int_{-\infty}^{\infty} (x - \mu)^2 f(x) dx = k\sigma^2.$$
 (3)

Combining equations (2) and (3) yields

$$\operatorname{Var}(\bar{X}_{RSS}) = \frac{\sigma^2}{k} - \frac{1}{k^2} \sum_{i=1}^{k} (\mu_{[i]} - \mu)^2 \le \operatorname{Var}(\bar{X}_{SRS}).$$

Al-Saleh and Al-kadiri (2000) extended the usual concept of RSS to to double ranked set sampling (DRSS) with the aim of constructing improved estimators of the population as compared with those associated with RSS and SRS. Subsequently, Al-Saleh and Al-Omari (2002) introduced multistage ranked set sampling (MSRSS), as a generalization of DRSS, and showed that estimators based on MSRSS dominate those obtained by DRSS. The MSRSS scheme can be summarized as follows.

- 1. Randomly identify  $k^{r+1}$  units from the population of interest, where r is the number of stages.
- 2. Allot the  $k^{r+1}$  units randomly into  $k^{r-1}$  sets of  $k^2$  units each.
- 3. For each set in step 2, apply 1-2 of RSS procedure explained above, to get a (judgement) ranked set of size k. This step gives  $k^{r-1}$  (judgement) ranked sets, each of size k.
- 4. Without actual measuring of the ranked sets, apply step 3 on the  $k^{r-1}$  ranked set to gain  $k^{r-2}$  second stage (judgement) ranked sets, of size k each.
- 5. Repeat step 3, without any actual measurement, until an *r*th stage (judgement) ranked set of size *k* is acquired.
- 6. Actually measure the *k* identified units in step 5.
- 7. Repeat steps 1-6, h times, if necessary, to obtain an rth stage ranked set sample of size n = hk.

In analogy with the previous notation, the rth stage ranked set sample will be denoted by  $\{X_{[i]j}^{(r)}: i=1,\ldots,k; j=1,\ldots,h\}$ . Two special cases of r=1 and r=2 in MSRSS coincide with RSS and DRSS, respectively.

Goodness-of-fit tests are used to decide whether an observed sample can be considered as a set of independent realization from a given CDF  $F_0$ . More precisely, they are used to test the hypothesis  $H_0: F = F_0$ , with F being the true CDF of the observations. For a review of goodness-of-fit tests based on SRS refer to the book by D'Agostino and Stephens (1986). Testing hypotheses on the parameters of classical distributions using ranked set samples have been developed in a large number of papers. However, this is not true in the case of test of fit, and a limited number of works are available on this topic. Stokes and Sager (1988) exploited RSS in estimating CDF. They proposed RSS analogue of Kolmogorov-Smirnov (KS) test and derived the null distribution of the test statistic.

Some distributions like normal, exponential and uniform have received much attention in the literature because of their tractable mathematical form. This is true in the

case of RSS and its variations. For example, estimation of parameters and quantiles of uniform distribution using generalized ranked-set sampling have been investigated (e.g., Adatia, 2003; Adatia and Ehsanes Saleh, 2004). In practical situations, however, the distributional form of the population is rarely known. Thus, application of these customized inferential methods is dependent on the availability of appropriate testing procedures for the assumptions of uniformity. Given a sample size, relative precision (RP) of the RSS estimator of the population mean with respect to its SRS counterpart (defined as the variance of the SRS mean divided by the variance of the RSS mean) differs according to the underlying distribution of the data, and is bounded above by (k+1)/2 for continuous distributions (1 < RP < (k+1)/2) (where k is the set size with which the ranked set sample is collected), with the upper bound achieved only for the uniform distribution. We may be interested to know whether the RSS has the highest efficiency over SRS in estimating the population mean in a specific situation. This could be another reason for developing uniformity test based on RSS.

As an information-theoretic measure of uncertainty, Shannon (1948) proposed entropy of a distribution, and proved that the entropy of normal distribution exceeds that of any other distribution with a density having the same variance. Vasicek (1976) used this property to introduce a test of the composite hypothesis of normality, and impressed development of tests of fit for other distributions. Such entropy-based tests of fit are available for some other distributions. See Dudewicz and van der Meulen (1981), Gokhale (1983), Grzegorzewski and Wieczorkowski (1999), and Mudholkar and Tian (2002). In this paper, we tackle the problem of testing uniformity, with an entropy-based approach, when the researcher obtains data using RSS and MSRSS. Similar procedures for the inverse Gaussian law was suggested by Mahdizadeh and Arghami (2010).

The paper proceeds as follows. In Section 2, some basic notions from information theory are reviewed, entropy based tests of uniformity based on RSS and MSRSS are suggested, and critical values of the respective test statistics are provided for some sample sizes. Power properties of the new tests are assessed by means of simulations whose results are reported in Section 3. A summary completes the paper in Section 4.

## 2. The tests

Entropy of a distribution F(x) with density function f(x) is defined as

$$H(f) = -\int_{-\infty}^{\infty} f(x) \log f(x) dx. \tag{4}$$

Vasicek (1976) presented a nonparametric entropy estimator for H(f) based on spacings of sample order statistics. The estimator called sample entropy is given by

$$V_{m,n}(f_X) = \frac{1}{n} \sum_{i=1}^{n} \log\left(\frac{n}{2m} (X_{(i+m)} - X_{(i-m)})\right),\tag{5}$$

where  $X_{(1)}, \ldots, X_{(n)}$  are the ordered values of a random sample of size n from F,  $X_{(j)} = X_{(1)}$ , if j < 1,  $X_{(j)} = X_{(n)}$ , if j > n and the window size m is a positive integer such that  $m \le n/2$ . This estimator is derived by expressing (4) in the form

$$H(f) = \int_0^1 \log\left(\frac{d}{du}F^{-1}(u)\right) du,$$

replacing the distribution F by the empirical distribution function, and using a difference operator instead of the differential operator.

Since entropy estimator (5) is based on spacings, one would need ordered values of the ranked set sample to estimate entropy in RSS. Imitating the SRS case, we first pool the units in all cycles and then form the estimator based on the ordered pooled sample. The MSRSS analogue of  $V_{m,n}(f_X)$  turns out to be

$$V_{m,n}^{(r)}(f_X) = \frac{1}{n} \sum_{i=1}^n \log \left( \frac{n}{2m} (X_{(i+m)}^{(r)} - X_{(i-m)}^{(r)}) \right),$$

where  $X_{(a)}^{(r)}$  is the *a*th (a = 1, ..., n) order statistic of the *r*th stage ranked set sample. From now on, the estimator (5) will be denoted by  $V_{m,n}^{(0)}(f_X)$ .

A simulation study was undertaken to compare the proposed estimators of entropy when the uniform U(0,1) is the underlying distribution. Table 1 displays simulated biases and root mean square errors (RMSEs) of  $V_{m,n}^{(r)}$  for r=0,1,2 based on 10,000 samples with n=10,20,30, and k=10 in MSRSS design (this setup is retained throughout the paper). It is seen that MSRSS improves entropy estimation with respect to SRS for given m and n. Besides, as the stage number increases, the absolute bias, and RMSE of the corresponding estimator diminishes.

Consider a random sample  $X_1, ..., X_n$  from a population having a density function f with the support (0,1) and suppose it is of interest to verify  $H_0: X \sim U(0,1)$  versus  $H_1: \sim H_0$ . It is well-known that for an f concentrated on (0,1) we have  $H(f) \leq 0$ , and the maximum value of H(f) is uniquely attained by the U(0,1) density (see Ash, 1965). Based on this result, Dudewicz and van der Meulen (1981) developed a test of  $H_0$ . Their test procedure is alternatively defined by the critical region

$$T_{m,n}(f_X) = \exp(V_{m,n}(f_X)) \le T_{m,n,\alpha}^*(f_X),$$

where  $T_{m,n,\alpha}^*(f_X)$  is the  $100\alpha$  percentile of the null distribution of  $T_{m,n}(f_X)$ . It can be shown, using convexity and Jensen's inequality, that  $V_{m,n}(f_X) \leq 0$  for all f on (0,1).

**Table 1:** Simulated biases and RMSEs of  $V_{m,n}^{(r)}(f)$  (r = 0, 1, 2) for the U(0,1) distribution with H(f) = 0.

		SRS		RSS		DRSS	
n	m	Bias	RMSE	Bias	RMSE	Bias	RMSE
10	1	-0.5192	0.5709	-0.4007	0.4469	-0.3262	0.3692
	2	-0.4112	0.4478	-0.3085	0.3348	-0.2598	0.2778
	3	-0.4223	0.4532	-0.3272	0.3430	-0.2968	0.3067
	4	-0.4580	0.4866	-0.3715	0.3831	-0.3477	0.3541
	5	-0.5026	0.5282	-0.4256	0.4360	-0.4043	0.4101
20	1	-0.3955	0.4193	-0.3420	0.3646	-0.3088	0.3299
	2	-0.2718	0.2903	-0.2194	0.2351	-0.1894	0.2027
	3	-0.2547	0.2712	-0.2048	0.2160	-0.1826	0.1919
	4	-0.2609	0.2751	-0.2153	0.2242	-0.1987	0.2054
	5	-0.2783	0.2908	-0.2349	0.2420	-0.2212	0.2262
	6	-0.2972	0.3080	-0.2592	0.2650	-0.2478	0.2518
	7	-0.3230	0.3336	-0.2859	0.2908	-0.2755	0.2787
	8	-0.3468	0.3567	-0.3141	0.3184	-0.3041	0.3068
	9	-0.3772	0.3871	-0.3425	0.3468	-0.3344	0.3370
	10	-0.4041	0.4133	-0.3708	0.3747	-0.3637	0.3661
30	1	-0.3539	0.3697	-0.3210	0.3360	-0.2978	0.3118
	2	-0.2247	0.2373	-0.1917	0.2024	-0.1698	0.1795
	3	-0.1980	0.2089	-0.1642	0.1725	-0.1464	0.1538
	4	-0.1954	0.2049	-0.1639	0.1708	-0.1484	0.1542
	5	-0.2016	0.2101	-0.1719	0.1776	-0.1605	0.1651
	6	-0.2136	0.2211	-0.1850	0.1899	-0.1749	0.1788
	7	-0.2273	0.2342	-0.2000	0.2041	-0.1922	0.1954
	8	-0.2441	0.2509	-0.2179	0.2214	-0.2104	0.2131
	9	-0.2596	0.2655	-0.2354	0.2385	-0.2286	0.2308
	10	-0.2769	0.2826	-0.2543	0.2572	-0.2482	0.2501
	11	-0.2948	0.3003	-0.2736	0.2762	-0.2681	0.2698
	12	-0.3138	0.3191	-0.2921	0.2946	-0.2880	0.2897
	13	-0.3329	0.3381	-0.3117	0.3142	-0.3070	0.3086
	14	-0.3508	0.3559	-0.3323	0.3347	-0.3272	0.3287
	15	-0.3702	0.3753	-0.3520	0.3544	-0.3473	0.3487

Thus, we used the exponential of the original test statistic in the above for mathematical nicety.

In order to obtain the percentiles of the null distribution,  $T_{m,n}(f_X)$  was calculated using the estimators  $V_{m,n}^{(r)}(f_X)$  for r=0,1,2 based on 10,000 samples of size n generated from the U(0,1) distribution. The values were then used to determine  $T_{m,n,0,1}^*(f_X)$  in different designs and for different sample sizes. Table 2 displays 0.1 critical points for the test statistics.

n	m	SRS	RSS	DRSS	n	m	SRS	RSS	DRSS
10	1	0.4329	0.5186	0.5730	30	1	0.6089	0.6374	0.6557
	2	0.5213	0.6197	0.6765		2	0.7215	0.7575	0.7801
	3	0.5267	0.6272	0.6725		3	0.7508	0.7894	0.8129
	4	0.5119	0.6084	0.6458		4	0.7569	0.7982	0.8143
	5	0.4881	0.5769	0.6091		5	0.7553	0.7940	0.8094
20	1	0.5576	0.6003	0.6325		6	0.7491	0.7852	0.7980
	2	0.6642	0.7185	0.7518		7	0.7387	0.7748	0.7892
	3	0.6871	0.7432	0.7706		8	0.7276	0.7631	0.7758
	4	0.6865	0.7425	0.7667		9	0.7153	0.7506	0.7624
	5	0.6783	0.7317	0.7532		10	0.7039	0.7380	0.7485
	6	0.6645	0.7178	0.7365		11	0.6914	0.7235	0.7346
	7	0.6490	0.7005	0.7173		12	0.6767	0.7098	0.7211
	8	0.6324	0.6811	0.6980		13	0.6640	0.6955	0.7071
	9	0.6141	0.6613	0.6768		14	0.6501	0.6816	0.6912
	10	0.5968	0.6416	0.6574		15	0.6379	0.6671	0.6758

Table 2: 0.1 critical points for the test statistics under SRS, RSS and DRSS designs.

The test statistics use the entropy estimators and there is no criteria to select the optimal window size associated with a given sample size in order to calculate these estimators. As a guide mentioned by some authors, the window size producing the largest critical value for a given n is apt to yield the highest power. In this sense, the optimal window size, denoted by  $m^*$ , at the significance level 0.1 for sample sizes 10, 20 and 30 are approximately 3, 3 and 4, respectively. Figure 1 shows a comparison of

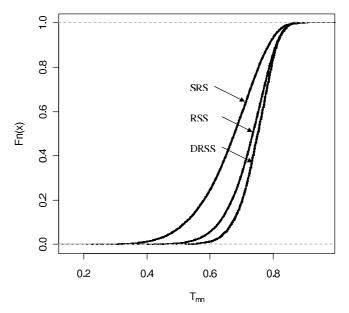


Figure 1: This figures compares the CDF of null distribution of T<sub>3,10</sub> under SRS, RSS and DRSS designs.

CDF of the test statistics in differen designs. It is observed that the null distribution of  $T_{3,10}$  under SRS (RSS) is stochastically smaller than that under RSS (DRSS) (a similar trend is observed for sample sizes n = 20,30). Thus, we expect the entropy test based on RSS (DRSS) to be more powerful than that based on SRS (RSS).

#### 3. Simulation results

A Monte Carlo simulation experiment is carried out to compare power of the entropy tests. We considered three classes of alternatives presented by Stephens (1974) which have been used by many authors. These alternatives specified by their distribution functions are

$$A(k): F(z) = 1 - (1-z)^k$$
  $0 \le z \le 1$   $(k = 1.5, 1.75, 2),$ 

$$B(k): F(z) = \begin{cases} 2^{k-1}z^k & 0 \le z \le 0.5\\ 1 - 2^{k-1}(1-z)^k & 0.5 \le z \le 1 \end{cases} \quad (k = 1.5, 1.75),$$

and

$$C(k): F(z) = \begin{cases} 0.5 - 2^{k-1}(0.5 - z)^k & 0 \le z \le 0.5 \\ 0.5 + 2^{k-1}(z - 0.5)^k & 0.5 \le z \le 1 \end{cases} \quad (k = 2, 2.5).$$

As compared with uniform, the first and second family give points closer to 0 and 0.5, respectively. And the third family gives points clustered at 0 and 1. We also considered Beta(2,2) as a symmetric distribution.

Under each design, 10,000 samples of sizes n = 10,20,30 were generated from each alternative distribution and the power of the tests were estimated by proportion of the samples falling into the corresponding critical region. Tables 3–6 exhibit the estimated power of the tests.

The results manifest that given a sample size, the entropy tests based on RSS and DRSS are more powerful than that based on SRS irrespective of the alternative distribution. Moreover, improved tests are obtained by increasing the sampling effort. That is DRSS has the best performance among three considered designs as is the case of entropy estimation. This could be traced to the fact that the test statistic in each design is constructed based on the corresponding entropy estimator. It is notable that RSS and DRSS do not have much to offer when power of SRS design is less than 0.1. We observe that for n = 10, the value m = 4 is best (in the sense that it yields the highest power) for the tests under most alternatives except C (for which m = 1 is best). For n = 20, best m for alternatives A, B and C are respectively 7, 10 and 2, while for n = 30 these are 10, 15 and 3. Given a sample size, best m is different according to the alternative

**Table 3:** Power comparison for the entropy tests of size 0.1 against alternatives A(1.5) and A(1.75).

			A(1.5)			A(1.75)	
n	m	SRS	RSS	DRSS	SRS	RSS	DRSS
10	1	0.1745	0.1879	0.1924	0.2431	0.2716	0.2887
	2	0.2182	0.2668	0.3360	0.3147	0.4198	0.5609
	3	0.2325	0.3306	0.4635	0.3451	0.5276	0.7142
	4	0.2397	0.3814	0.5285	0.3570	0.5766	0.7628
	5	0.2436	0.3794	0.5017	0.3503	0.5728	0.7396
20	1	0.2298	0.2367	0.2620	0.3474	0.3843	0.4356
	2	0.3052	0.3530	0.4098	0.4786	0.6022	0.7178
	3	0.3292	0.4351	0.5174	0.5342	0.7264	0.8413
	4	0.3704	0.5064	0.6030	0.5760	0.7956	0.9032
	5	0.3728	0.5301	0.6386	0.5817	0.8207	0.9186
	6	0.3846	0.5693	0.6962	0.5932	0.8494	0.9451
	7	0.3817	0.5867	0.7092	0.5870	0.8575	0.9482
	8	0.3754	0.5801	0.7126	0.5821	0.8490	0.9436
	9	0.3720	0.5718	0.6996	0.5713	0.8358	0.9322
	10	0.3681	0.5536	0.6812	0.5608	0.8114	0.9156
30	1	0.2737	0.2871	0.2890	0.4554	0.4962	0.5216
	2	0.3795	0.4287	0.4882	0.6026	0.7538	0.8430
	3	0.4260	0.5468	0.6324	0.6748	0.8710	0.9406
	4	0.4556	0.6195	0.6958	0.7106	0.9175	0.9748
	5	0.4821	0.6536	0.7476	0.7382	0.9387	0.9824
	6	0.4926	0.6783	0.7662	0.7512	0.9435	0.9870
	7	0.5016	0.6985	0.8210	0.7533	0.9516	0.9936
	8	0.5137	0.7245	0.8344	0.7642	0.9578	0.9945
	9	0.5068	0.7352	0.8490	0.7618	0.9622	0.9934
	10	0.5184	0.7510	0.8538	0.7723	0.9651	0.9927
	11	0.5170	0.7486	0.8612	0.7674	0.9601	0.9954
	12	0.4996	0.7442	0.8569	0.7505	0.9570	0.9932
	13	0.4954	0.7355	0.8556	0.7410	0.9513	0.9942
	14	0.4825	0.7190	0.8230	0.7295	0.9372	0.9900
	15	0.4768	0.6925	0.7942	0.7153	0.9241	0.9786

**Table 4:** Power comparison for the entropy tests of size 0.1 against alternatives A(2) and B(1.5).

			A(2)			B(1.5)	
n	m	SRS	RSS	DRSS	SRS	RSS	DRSS
10	1	0.3181	0.3742	0.4107	0.1948	0.2245	0.2310
	2	0.4254	0.5969	0.7821	0.2716	0.3520	0.4633
	3	0.4635	0.7208	0.8913	0.3188	0.4795	0.6490
	4	0.4674	0.7648	0.9134	0.3425	0.5734	0.7572
	5	0.4612	0.7430	0.8882	0.3609	0.6026	0.7698
20	1	0.4983	0.5712	0.6344	0.2417	0.2672	0.2856
	2	0.6541	0.8348	0.9318	0.3458	0.4236	0.4978
	3	0.7103	0.9221	0.9830	0.3973	0.5324	0.6206
	4	0.7472	0.9532	0.9926	0.4564	0.6213	0.7230
	5	0.7624	0.9608	0.9952	0.4900	0.6792	0.7844
	6	0.7718	0.9680	0.9964	0.5140	0.7328	0.8465
	7	0.7697	0.9735	0.9972	0.5406	0.7760	0.8751
	8	0.7562	0.9658	0.9948	0.5510	0.8035	0.8924
	9	0.7445	0.9567	0.9931	0.5636	0.8142	0.9172
	10	0.7320	0.9453	0.9876	0.5727	0.8210	0.9204
30	1	0.6324	0.7255	0.7740	0.2911	0.3128	0.3397
	2	0.8009	0.9472	0.9872	0.4085	0.4939	0.5516
	3	0.8613	0.9861	0.9986	0.4821	0.6174	0.7050
	4	0.8870	0.9934	0.9998	0.5349	0.6960	0.7812
	5	0.9010	0.9963	1.0000	0.5719	0.7486	0.8305
	6	0.9084	0.9968	1.0000	0.6034	0.7764	0.8570
	7	0.9142	0.9980	0.9998	0.6170	0.8123	0.8996
	8	0.9175	0.9985	1.0000	0.6452	0.8375	0.9230
	9	0.9151	0.9984	0.9998	0.6636	0.8681	0.9408
	10	0.9182	0.9992	1.0000	0.6901	0.8894	0.9562
	11	0.9135	0.9981	1.0000	0.7004	0.9045	0.9636
	12	0.9064	0.9977	1.0000	0.7088	0.9173	0.9748
	13	0.8998	0.9964	1.0000	0.7190	0.9257	0.9782
	14	0.8890	0.9932	1.0000	0.7201	0.9212	0.9718
	15	0.8756	0.9925	0.9996	0.7236	0.9220	0.9706

**Table 5:** Power comparison for the entropy tests of size 0.1 against alternatives B(1.75) and C(2).

			B(1.75)			C(2)	
n	m	SRS	RSS	DRSS	SRS	RSS	DRSS
10	1	0.2696	0.3250	0.3514	0.2082	0.2431	0.2487
	2	0.3875	0.5339	0.6872	0.1430	0.1829	0.2151
	3	0.4612	0.6872	0.8495	0.0647	0.0483	0.0465
	4	0.5026	0.7831	0.9155	0.0475	0.0069	0.0009
	5	0.5219	0.8106	0.9287	0.0296	0.0025	0.0004
20	1	0.3815	0.4294	0.4830	0.4006	0.4483	0.5054
	2	0.5372	0.6652	0.7646	0.4324	0.5364	0.6298
	3	0.6054	0.7884	0.8820	0.3662	0.4892	0.5904
	4	0.6687	0.8607	0.9381	0.2751	0.3866	0.4613
	5	0.7018	0.8939	0.9562	0.1416	0.1989	0.2258
	6	0.7351	0.9210	0.9742	0.0626	0.0548	0.0476
	7	0.7600	0.9469	0.9834	0.0372	0.0062	0.0030
	8	0.7684	0.9573	0.9858	0.0261	0.0014	0.0002
	9	0.7842	0.9618	0.9902	0.0208	0.0007	0.0000
	10	0.7890	0.9624	0.9944	0.0149	0.0004	0.0000
30	1	0.4742	0.5268	0.5600	0.5574	0.6159	0.6627
	2	0.6537	0.7695	0.8597	0.6590	0.7601	0.8653
	3	0.7351	0.8835	0.9443	0.6512	0.7963	0.8977
	4	0.7867	0.9287	0.9725	0.6032	0.7654	0.8693
	5	0.8136	0.9508	0.9873	0.5244	0.6888	0.7830
	6	0.8362	0.9621	0.9897	0.4213	0.5626	0.6690
	7	0.8514	0.9723	0.9906	0.2789	0.4130	0.5117
	8	0.8725	0.9782	0.9950	0.1507	0.2194	0.2453
	9	0.8799	0.9847	0.9962	0.0652	0.0672	0.0705
	10	0.8980	0.9906	0.9967	0.0338	0.0097	0.0067
	11	0.9061	0.9912	0.9990	0.0241	0.0008	0.0000
	12	0.9078	0.9926	0.9993	0.0176	0.0003	0.0003
	13	0.9134	0.9953	1.0000	0.0142	0.0004	0.0000
	14	0.9142	0.9938	0.9993	0.0097	0.0001	0.0000
	15	0.9187	0.9947	0.9997	0.0075	0.0000	0.0000

**Table 6:** Power comparison for the entropy tests of size 0.1 against alternatives C(2.5) and B(2,2).

			C(2.5)			B(2,2)	
n	m	SRS	RSS	DRSS	SRS	RSS	DRSS
10	1	0.3168	0.3782	0.4105	0.2630	0.3174	0.3496
	2	0.2124	0.2951	0.3884	0.3767	0.5336	0.6941
	3	0.0820	0.0672	0.0713	0.4382	0.6843	0.8560
	4	0.0506	0.0066	0.0005	0.4821	0.7805	0.9158
	5	0.0292	0.0018	0.0001	0.5064	0.8028	0.9275
20	1	0.6375	0.7308	0.8150	0.3713	0.4160	0.4682
	2	0.6932	0.8286	0.9361	0.5364	0.6647	0.7724
	3	0.6184	0.7948	0.9178	0.6171	0.7995	0.8843
	4	0.4951	0.6870	0.8216	0.6796	0.8713	0.9420
	5	0.2755	0.4264	0.5384	0.7204	0.9035	0.9600
	6	0.0978	0.1192	0.1374	0.7446	0.9351	0.9784
	7	0.0480	0.0071	0.0030	0.7657	0.9483	0.9860
	8	0.0326	0.0010	0.0000	0.7780	0.9609	0.9876
	9	0.0254	0.0004	0.0000	0.7832	0.9626	0.9915
	10	0.0169	0.0001	0.0000	0.7894	0.9610	0.9928
30	1	0.8298	0.8974	0.9457	0.4624	0.5109	0.5486
	2	0.9129	0.9740	0.9963	0.6508	0.7693	0.8460
	3	0.9064	0.9781	0.9990	0.7440	0.8832	0.9476
	4	0.8806	0.9738	0.9987	0.7974	0.9346	0.9704
	5	0.8246	0.9464	0.9943	0.8294	0.9540	0.9835
	6	0.7350	0.8897	0.9718	0.8545	0.9654	0.9884
	7	0.5681	0.7825	0.9196	0.8679	0.9766	0.9942
	8	0.3442	0.5314	0.6851	0.8834	0.9825	0.9960
	9	0.1338	0.1970	0.2430	0.8920	0.9879	0.9982
	10	0.0523	0.0218	0.0210	0.9056	0.9915	0.9994
	11	0.0327	0.0012	0.0000	0.9142	0.9923	0.9986
	12	0.0242	0.0003	0.0000	0.9165	0.9942	0.9991
	13	0.0170	0.0001	0.0000	0.9178	0.9948	0.9994
	14	0.0122	0.0001	0.0000	0.9160	0.9936	0.9992
	15	0.0097	0.0000	0.0000	0.9181	0.9943	0.9994

distribution. As a remedy, we may use data histogram to determine best window size for implementing the tests. Table 7 compares the power of RSS entropy based test for uniformity, when m is best, with that of the KS test whose results are given in italic. It is seen that entropy test shows remarkable dominance over the KS test against alternatives B and B(2,2), whereas the KS test is better for alternatives A and C.

**Table 7:** Power comparison for the entropy test and KS test of size 0.1 against several alternative distributions under RSS.

				Distribution				
n	A(1.5)	A(1.75)	A(2)	B(1.5)	B(1.75)	C(2)	C(2.5)	B(2,2)
10	0.381	0.577	0.765	0.603	0.811	0.243	0.378	0.803
	0.629	0.875	0.971	0.176	0.290	0.583	0.798	0.235
20	0.587	0.858	0.974	0.821	0.962	0.536	0.829	0.961
	0.884	0.993	1.000	0.327	0.566	0.845	0.975	0.482
30	0.751	0.965	0.999	0.922	0.995	0.796	0.978	0.994
	0.970	1.000	1.000	0.463	0.768	0.950	0.997	0.691

Table 8: 0.1 critical points of the test statistics under MSRSS designs.

		Stage Number	
$n(m^*)$	r=2	r=3	r=4
10(3)	0.6725	0.6910	0.7048
20(3)	0.7706	0.7892	0.7956
30(4)	0.8143	0.8236	0.8281

**Table 9:** Power comparison for the entropy tests of size 0.1 against several alternative distributions under MSRSS designs.

	Distribution											
$n(m^*)$	r	A(1.5)	A(1.75)	A(2)	B(1.5)	B(1.75)	C(2)	C(2.5)	B(2,2)			
10(3)	2	0.4635	0.7142	0.8913	0.6490	0.8495	0.2487	0.4105	0.8560			
	3	0.5371	0.7925	0.9467	0.7459	0.9011	0.2660	0.4419	0.9078			
	4	0.5940	0.8593	0.9702	0.7762	0.9304	0.3171	0.5295	0.9517			
20(3)	2	0.5174	0.8413	0.9830	0.6206	0.8820	0.5904	0.9178	0.8843			
	3	0.5866	0.8945	0.9956	0.6874	0.9268	0.6780	0.9732	0.9282			
	4	0.6218	0.9387	1.0000	0.7033	0.9409	0.7161	0.9846	0.9613			
30(4)	2	0.6958	0.9748	0.9998	0.7812	0.9725	0.8693	0.9987	0.9704			
	3	0.7340	0.9896	1.0000	0.8126	0.9893	0.9221	1.0000	0.9855			
	4	0.7535	1.0000	1.0000	0.8290	0.9984	0.9407	1.0000	1.0000			

Tables 2 and 3–6 were formed under MSRSS with r=3,4 to see whether further increase in power is achieved by increasing the stage number. Tables 8 and 9 contain 0.1 critical points and power of the tests, respectively. For a given n, the results are provided only for the optimal m, except for C family and n=10 where m=1 is applied. Also, results of DRSS design were included to ease comparison. From Table 9, we can see that as r increases, some improvement in power happens. The differences in results for r=2 and r=3,4 are less pronounced in large sample size, and thus we may restrict ourselves to DRSS in practice.

## 4. Conclusion

This article was directed at the problem of developing tests of uniformity under RSS and MSRSS designs. In line with the available entropy based test of fit in SRS, our tests use sample entropy based on the pre-mentioned designs. Simulation studies accompany the presentation to explore power behaviour of the proposed tests in finite sample sizes. The results disclose that RSS and its variations outperform SRS in constructing powerful entropy based test of uniformity. The authors have developed similar tests for other distributions (e.g. uniform, beta, exponential, gamma, log-normal, Pareto, Rayleigh, Weibull, normal, Laplace, etc.) using improved entropy estimators (e.g., see Ebrahimi et al. (1994) and Novi Inverardi (2003)). The results will be reported in separate works.

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